



# First steps of numerical simulation using Artificial Intelligence

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# First Steps of Numerical Simulation using Artificial Intelligence

**Vincent Vadez**

**Dorea**

**François Brunetti**

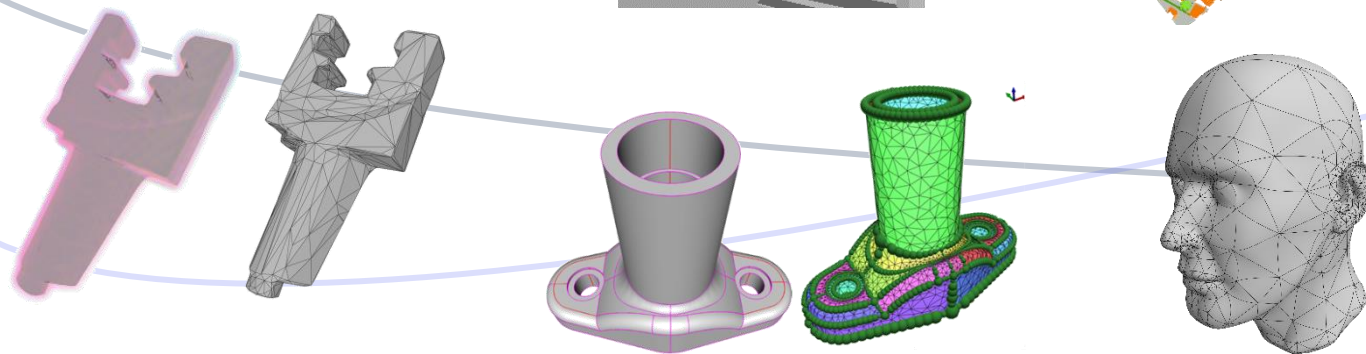
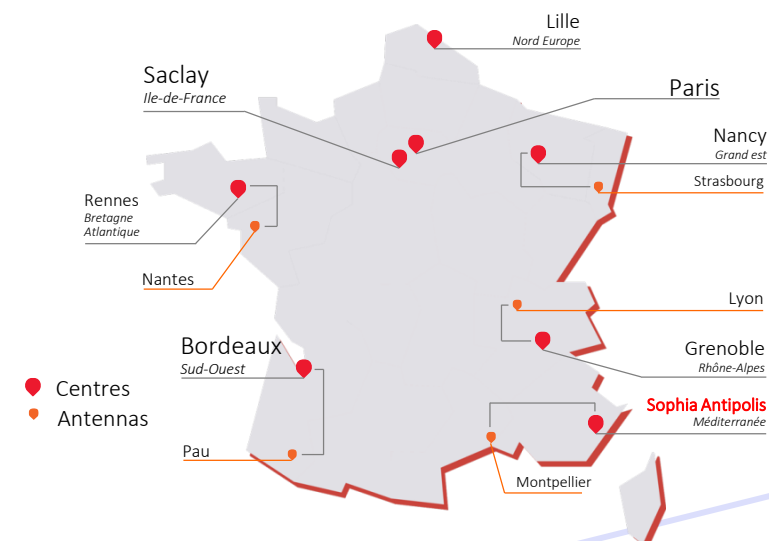
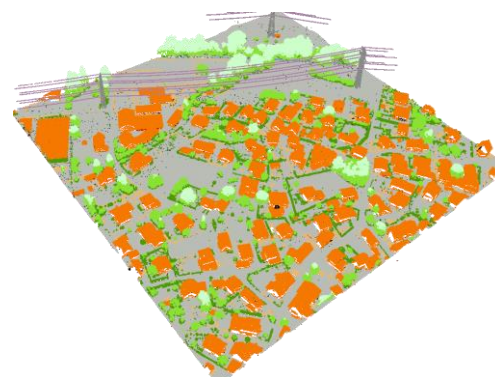
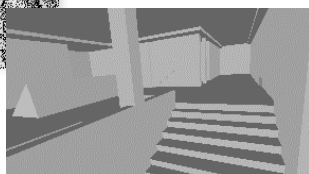
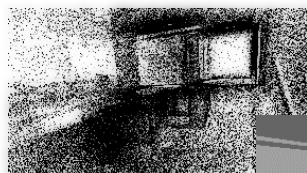
**Dorea**

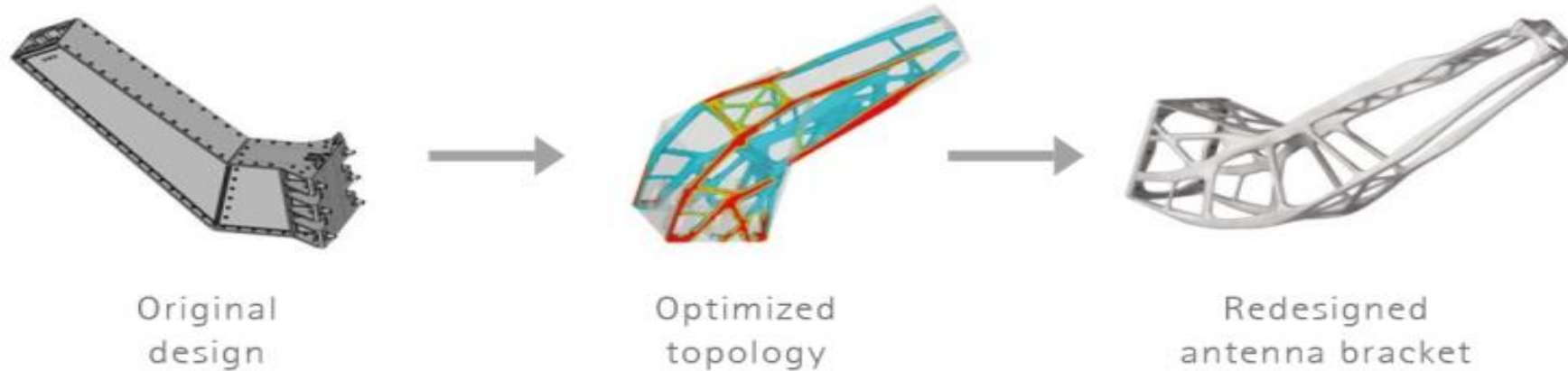
**Pierre Alliez**

**Inria Sophia Antipolis - Méditerranée**

## ▸ Geometric modeling of 3D scenes from measurement data

- Analysis, reconstruction, approximation
- Computational geometry, geometry processing, machine learning





- ▶ **Additive manufacturing yields increasingly complex objects**
  - ▶ Reduced weight via topology optimization
  - ▶ Many more facets elements are required to describe these free-form shapes, which are later added to the full satellite model.

- ▶ **Context of real-time simulation & sensibility**
  - ▶ Radiative thermal simulation is time-consuming:  $O(n^2)$  complexity for the view factors, with  $n$  the number of faces of the mesh.
  - ▶ Full simulation intractable on the complete satellite model, in a reasonable time.
  - ▶ A thermal-aware geometric approximation process is required, allowing real-time simulation and beyond (multi-physics simulation and predictions).

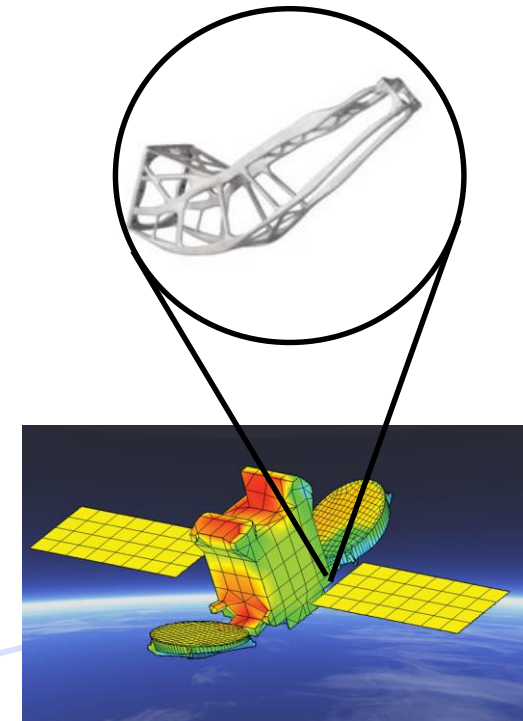


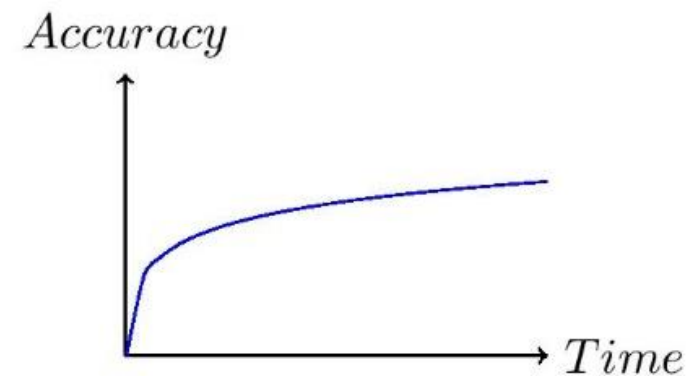
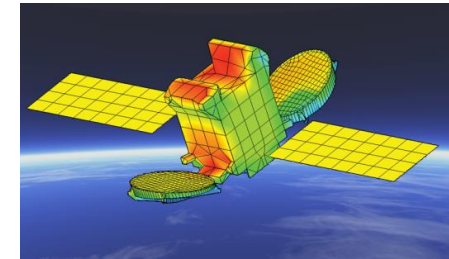
Image from [www.ata-e.com](http://www.ata-e.com)

# PROBLEM STATEMENT

- ▶ **Input:** Complex surface mesh (many facets and occlusions, created by a CAD software)
- ▶ **Output:** Approximated model respecting the view factors of the thermal nodes
- ▶ **Guarantees:** Error bounds under wide range of configurations and conditions
- ▶ **Goal:** Optimize trade-off between accuracy and time



SOLIDWORKS  
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- ▶ **Topic of Ph.D. thesis:** Design a geometric approximation method preserving a *simulation-aware* error metric rather than a geometric error metric.
- ▶ **Application to space thermal analysis:** view factor computation and model reduction
- ▶ **Goals:**
  - ▶ Compute reference view factors
  - ▶ Compare with approximated view factors
  - ▶ Evaluate simulation with approximation
  - ▶ Utilize supervised machine learning to automate the reduction process, leveraging a large training dataset.

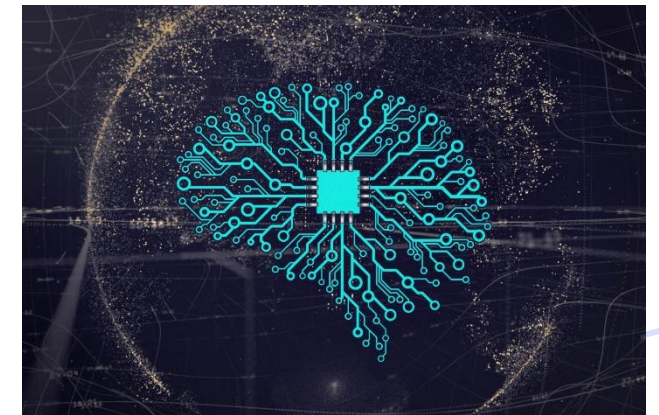


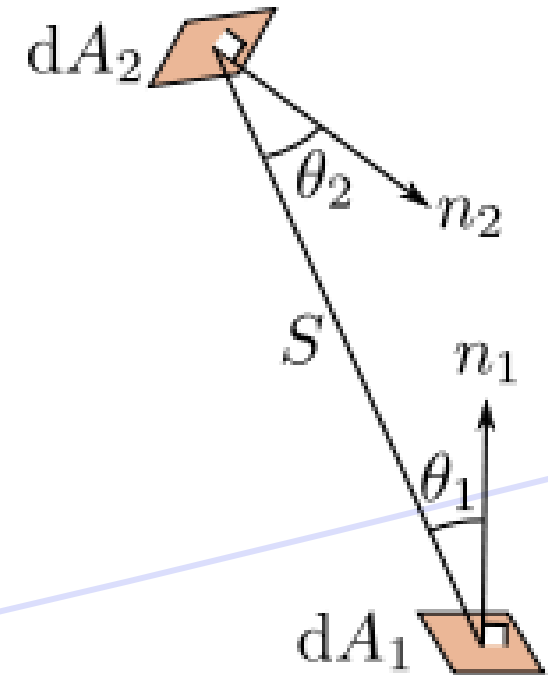
Image from [www.warontherocks.com](http://www.warontherocks.com)

$$F_{1 \rightarrow 2} = \frac{1}{A_1} \int_{A_1} \int_{A_2} \frac{\cos \theta_1 \cos \theta_2}{\pi s^2} dA_2 dA_1$$

$$dF_{1 \rightarrow 2} = \frac{\cos \theta_1 \cos \theta_2}{\pi s^2} dA_2$$

View factors depend on 3 components:

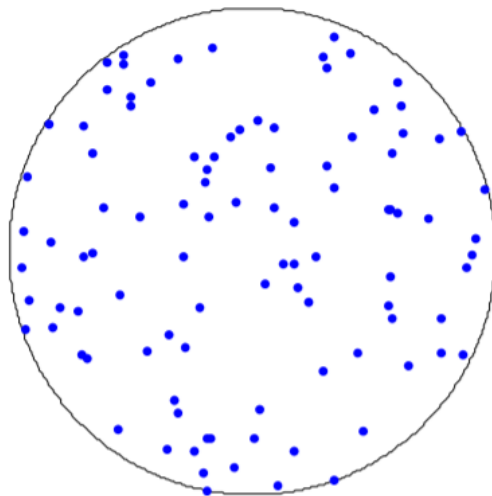
- area of the faces
- distance between them
- orientation



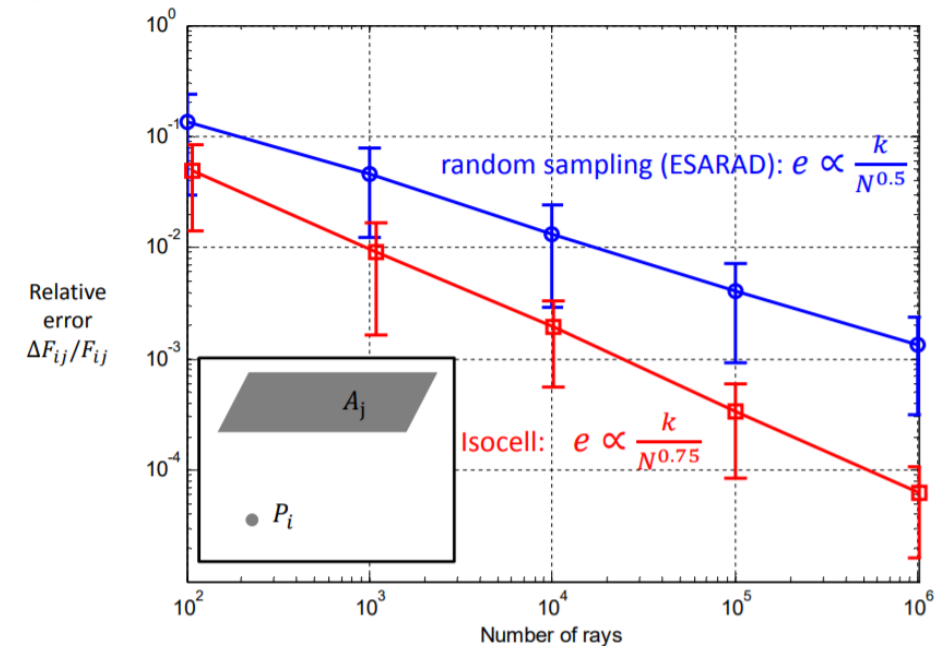
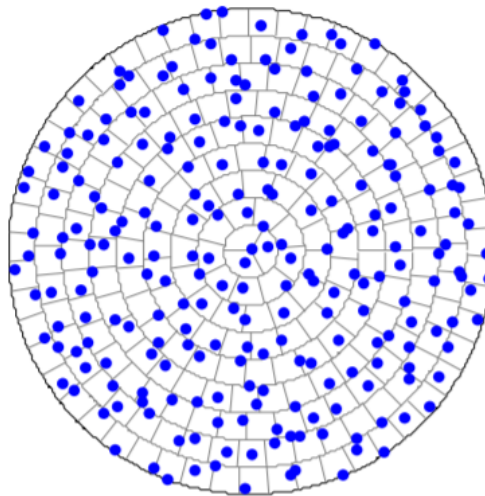


- ▶ **Accelerating computation of view factors**
  - ▶ **Jacques, Masset, Kerschen:** Ray tracing enhancement for space thermal analysis: isocell method, 27th Space Thermal Analysis Workshop, ESTEC.

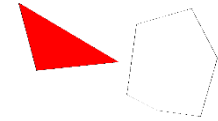
Random (classic) sampling



Isocell sampling

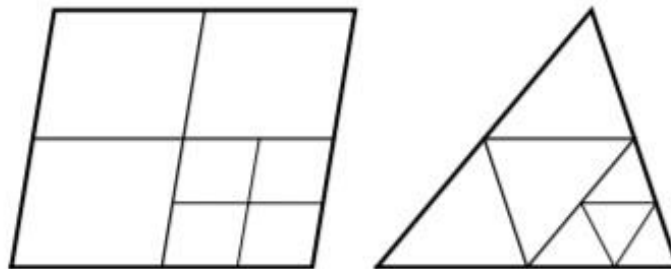


- ▶ **Schröder, Hanrahan**: *On the Form Factor between Two Polygons*. Proceedings of ACM SIGGRAPH 1993.  
→ Closed form solution for the view factor between two convex polygons
- ▶ **Walton**: *Calculation of Obstructed View Factors by Adaptive Integration*. NIST Report, 2002.

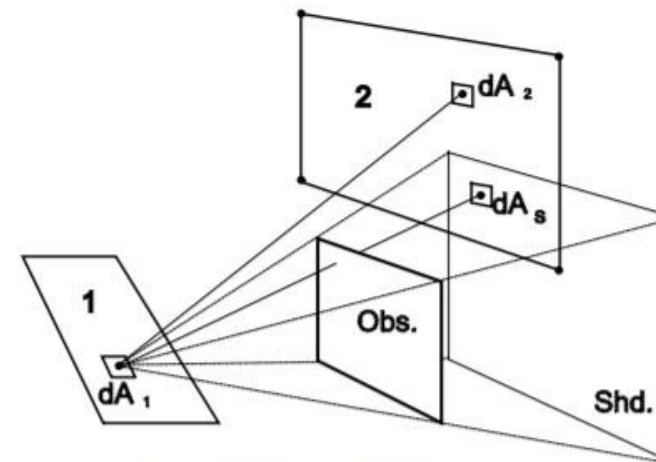


$$\begin{aligned}
 L(b|y) &:= \int^y t^2 (1-t^2)^{-1} \ln(b+t) dt = \frac{1}{b} \left[ \frac{-b \ln(b-t)}{1-t^2} - \frac{b \ln(b+t)}{1+t^2} + \left( \frac{2b^2-1}{1-t^2} \ln \frac{1-t}{1+t} + \ln \frac{1-t}{1+t} \right) \ln(b+t) \right] \\
 &\quad + \frac{2b^2-1}{1-t^2} \ln \frac{1-t}{1+t} + L_2 \left( \frac{1-t}{1+t} \right) \\
 M(y) &:= \int^y t^2 (1-t^2)^{-1} dt = \frac{1}{2} \left[ 4y(y^2-1)^{-1} + 2y(y^2-1)^{-1} + \ln \frac{y+1}{y-1} \right] \\
 G(q|y) &:= \int^y \ln q(t) dt = \frac{x'_0}{2} \ln q(y) - 2y + \frac{1}{2} \tan^{-1} \frac{x'_0}{y} \\
 H(q|y) &:= \int^y t \ln q(t) dt = \left( \frac{y^2}{2} + \frac{y}{2} - \frac{1}{2y} \right) \ln q(y) - \frac{y \ln y}{2} - \frac{1}{2y} \tan^{-1} \frac{x'_0}{y}
 \end{aligned}$$

Closed form  
(without obstruction)

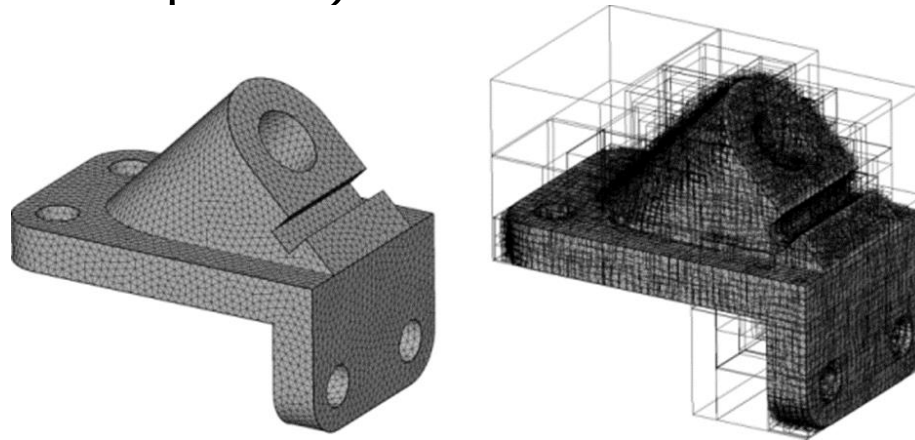


Adaptive Division of Polygons



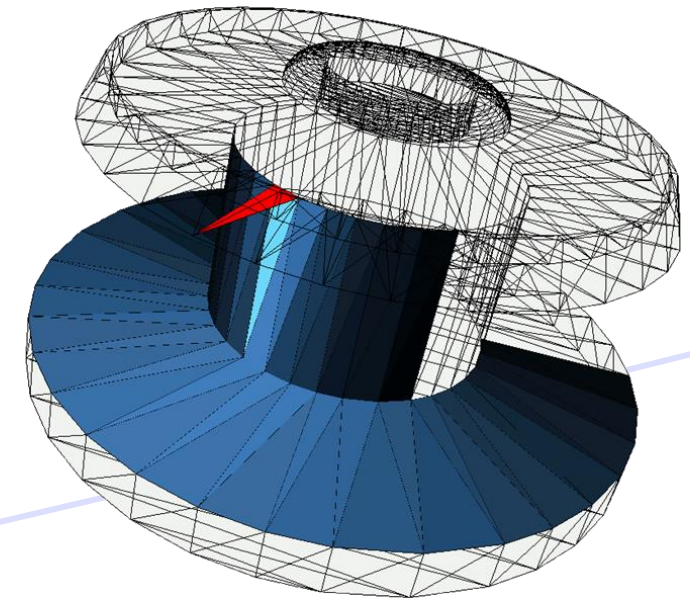
Partially Obstructed View

- ▶ **Hierarchical geometric data structure: AABB-tree** (fast intersection queries)



CGAL

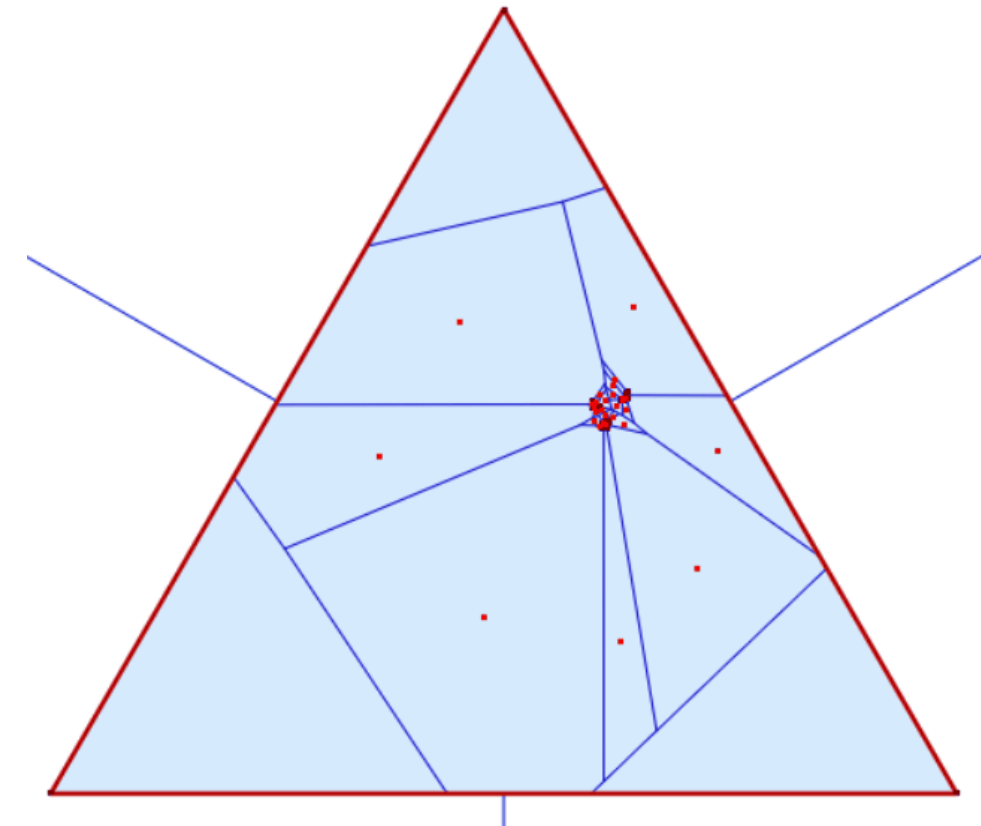
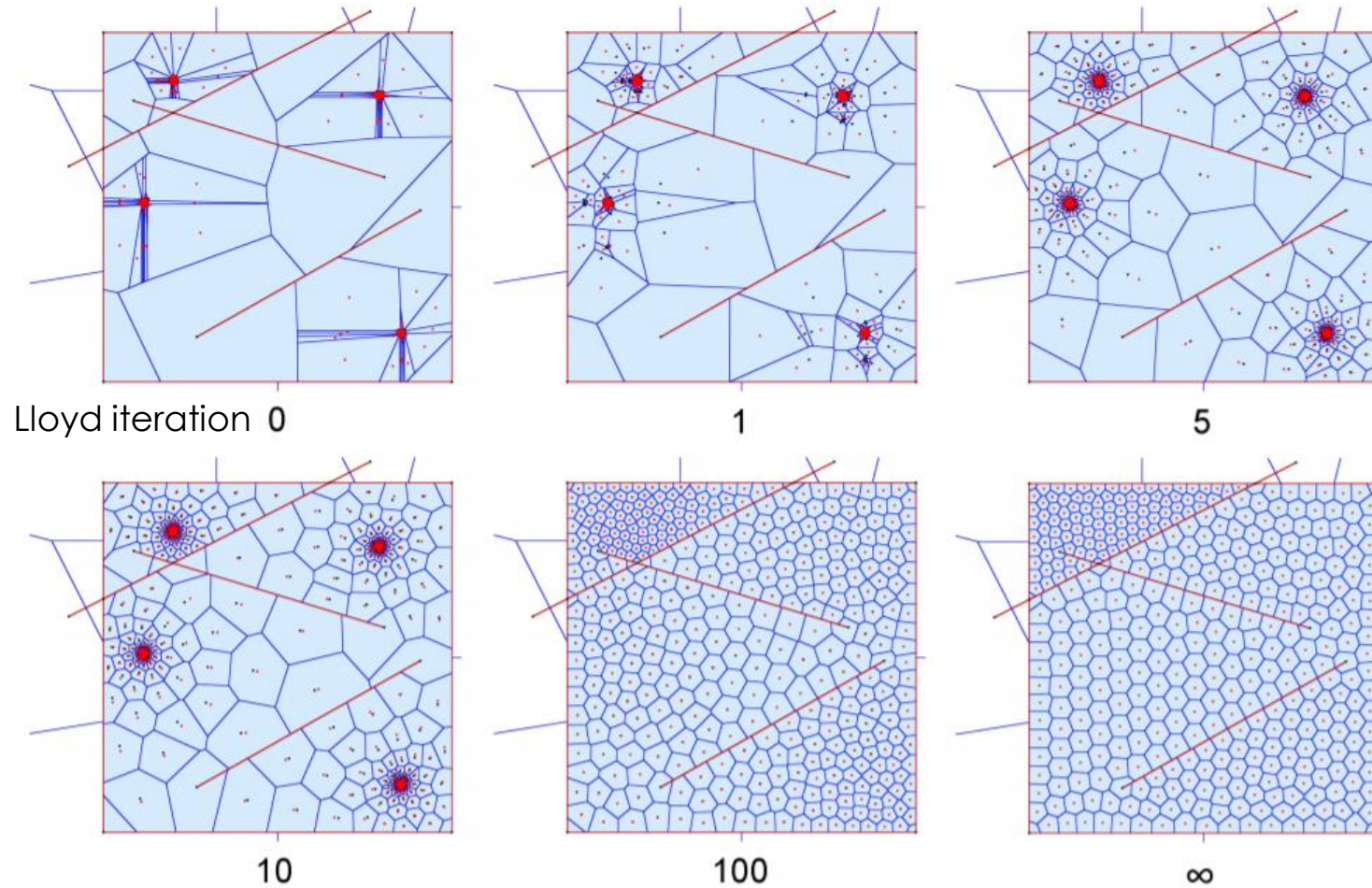
- ▶ **Closed form solution** when full visibility (**Schröder**)
- ▶ **Quadrature in the presence of occlusions:**
  - ▶ Point-based (via bounded centroidal Voronoi diagrams)
  - ▶ Triangle-based (recursive longest bisection)



Reference view factors



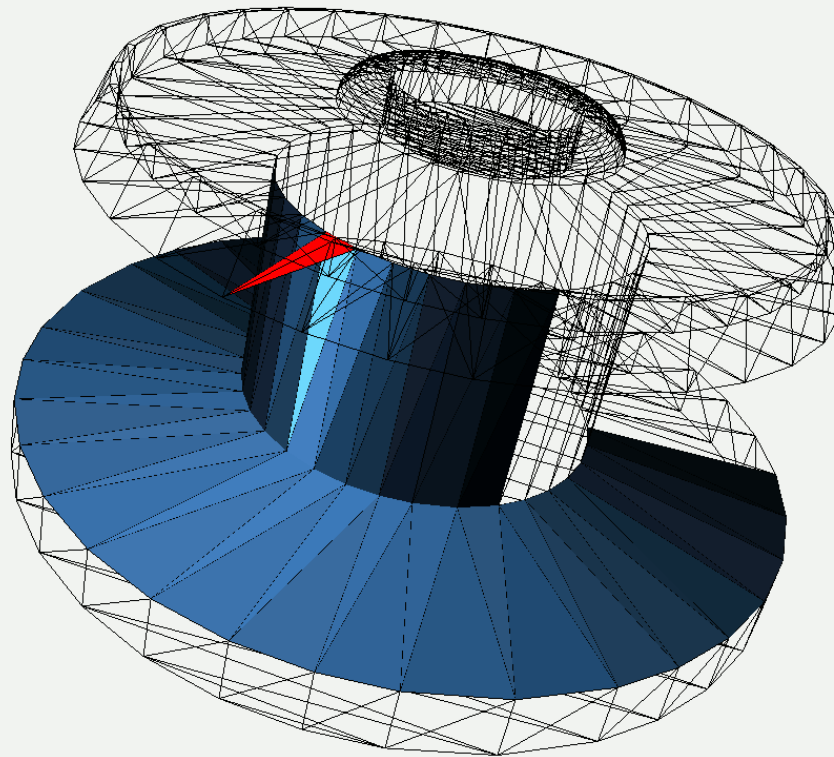
# Bounded Centroidal Voronoi Diagrams (CVD)



**Tournois, Alliez, Devillers:** 2D Centroidal Voronoi Tessellations with Constraints.

# VIEW FACTORS (VF)

File Algorithms View Validation



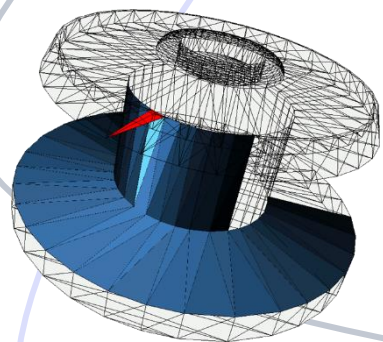
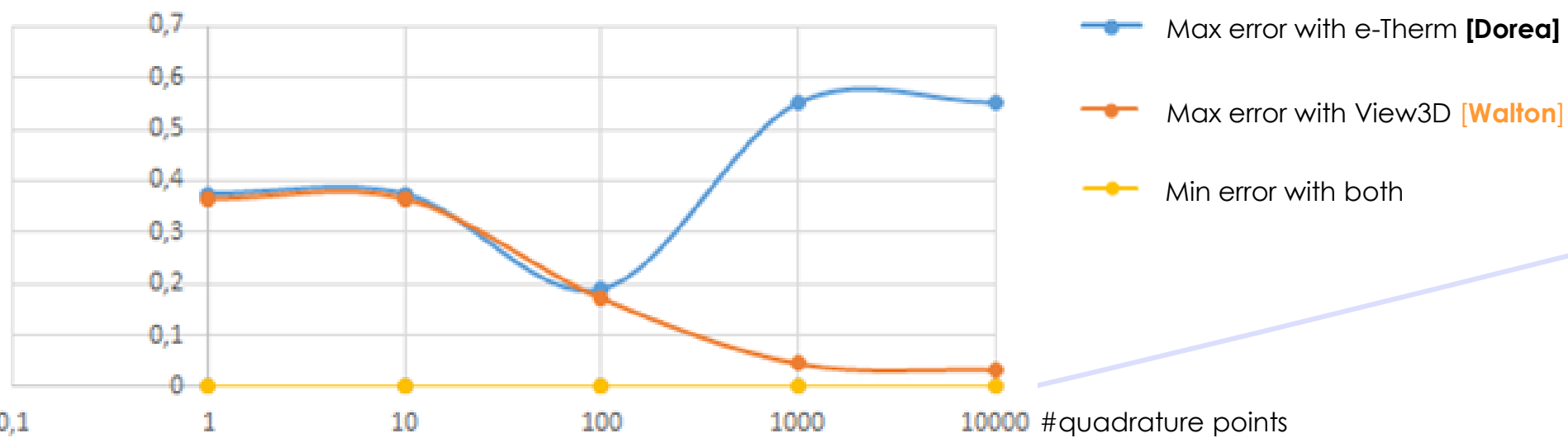
VF  
value



Emitter

# COMPARISONS

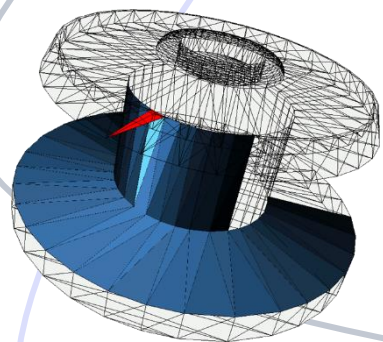
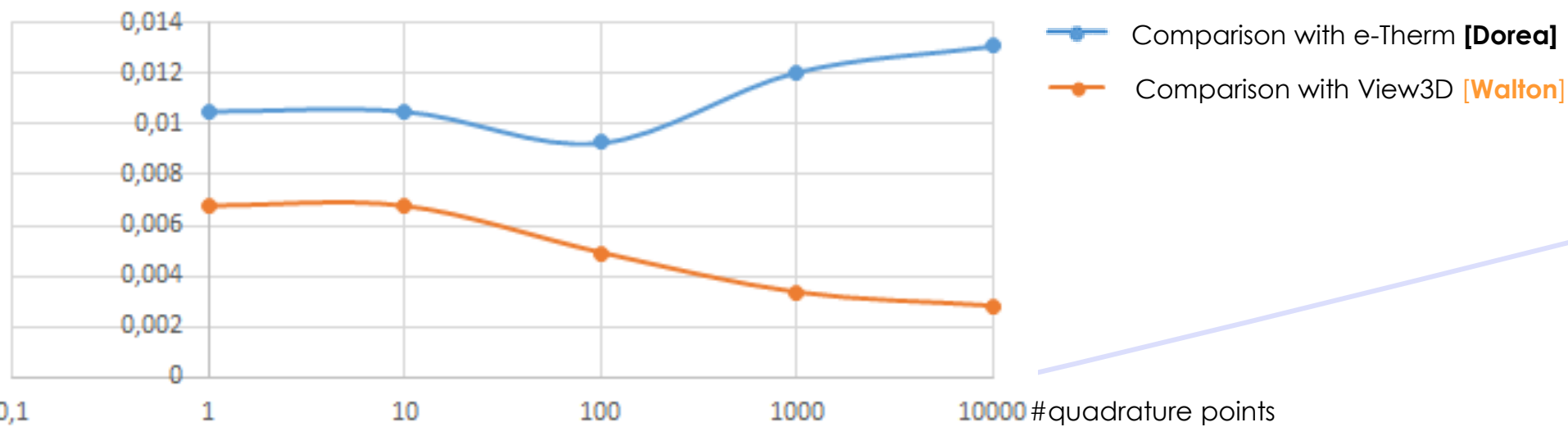
Maximum  
difference of  
view factors



0,1

# COMPARISONS

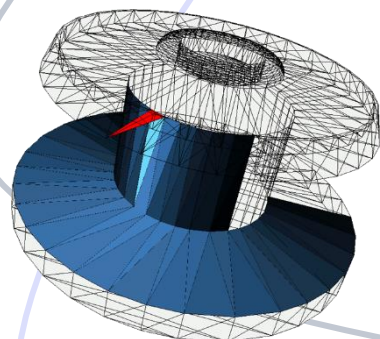
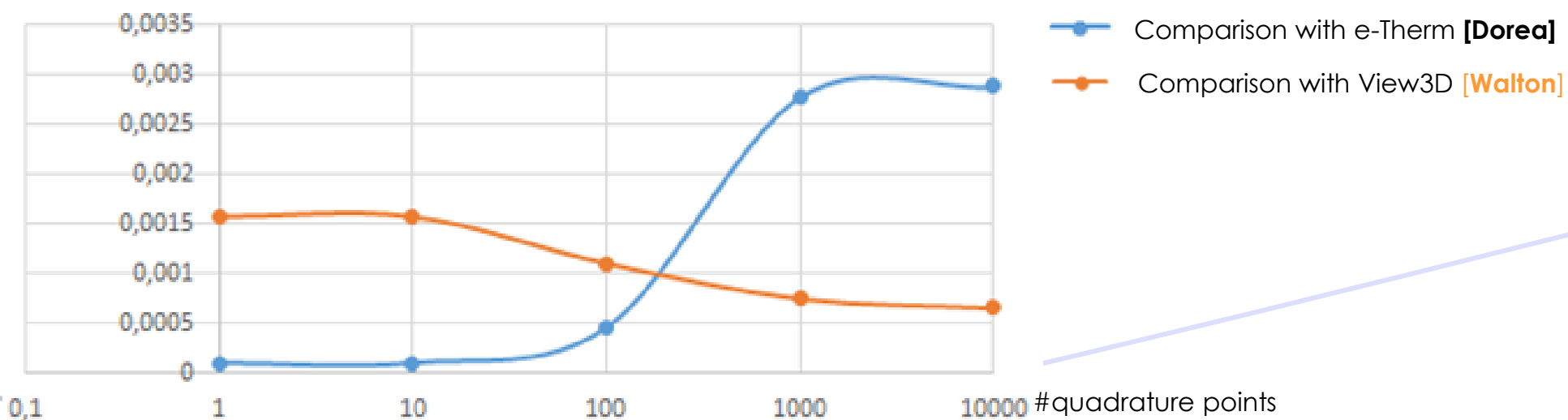
Standard  
deviation of  
view factor





# COMPARISONS

Average  
error of  
view factor

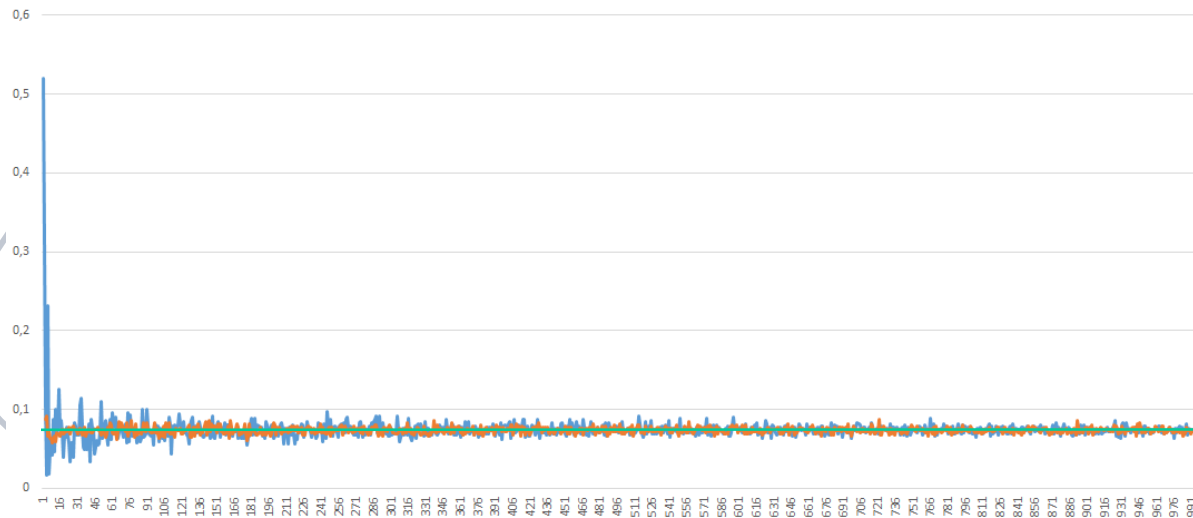


# RANDOM SAMPLING VS CVD

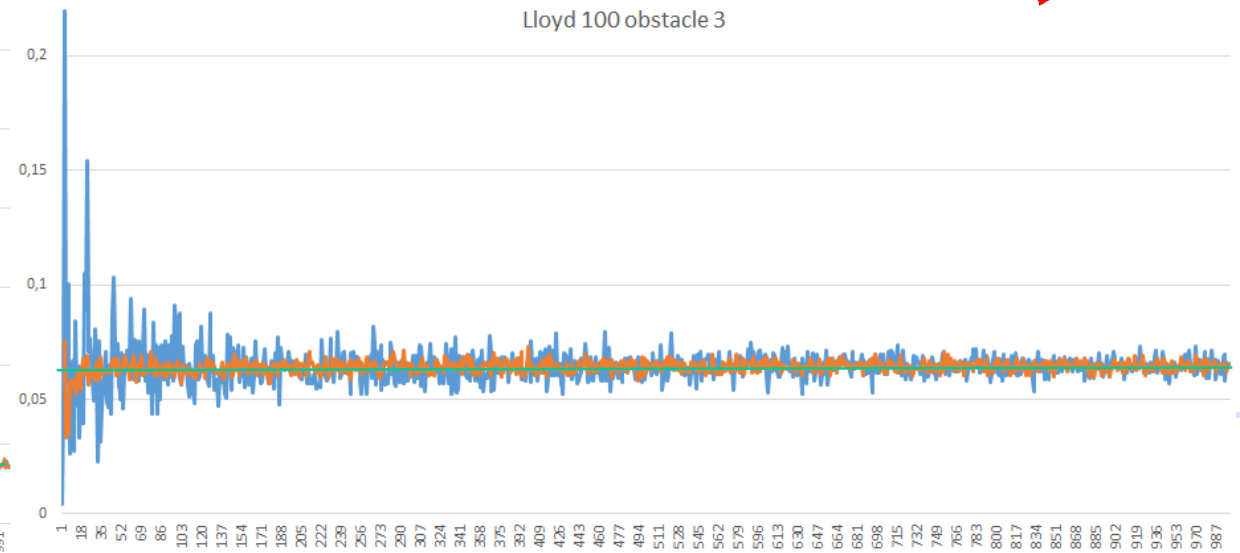
Results with two random triangles configuration and an obstacle between them

View factor value

Lloyd 100 obstacle 2



Lloyd 100 obstacle 3



#quadrature points

Random uniform sampling

Bounded Centroidal Voronoi

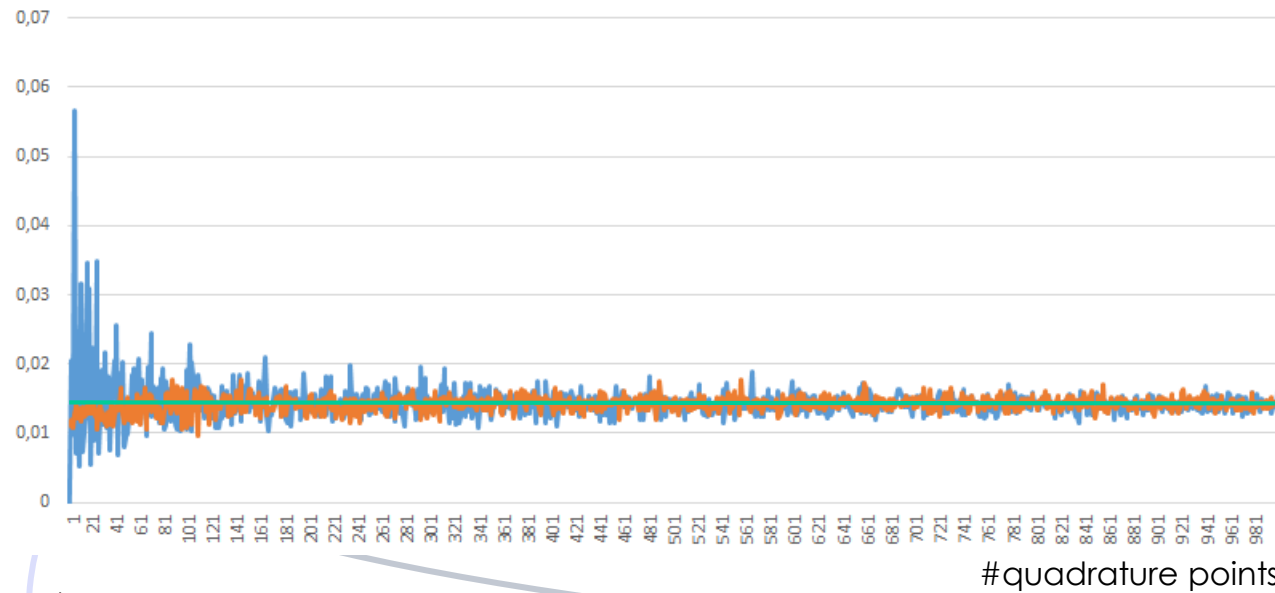
View factor exact value

# RANDOM SAMPLING VS CVD

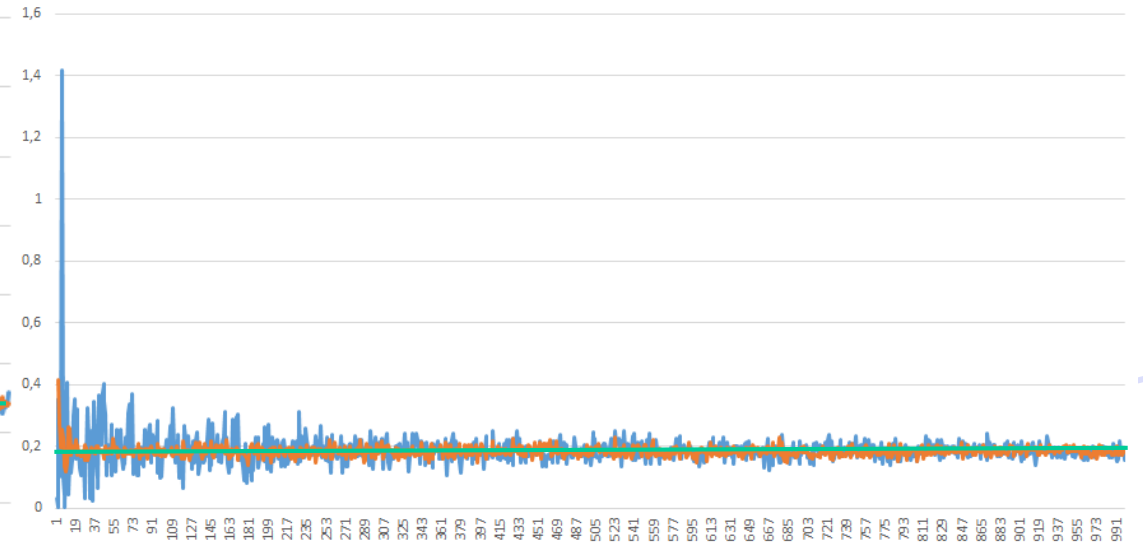
Results with two random triangles configuration and an obstacle between them

View factor value

Lloyd 100 obstacle 4



Lloyd 100 obstacle 5



#quadrature points

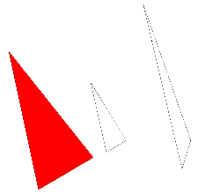
Random uniform sampling

Bounded Centroidal Voronoi

View factor exact value

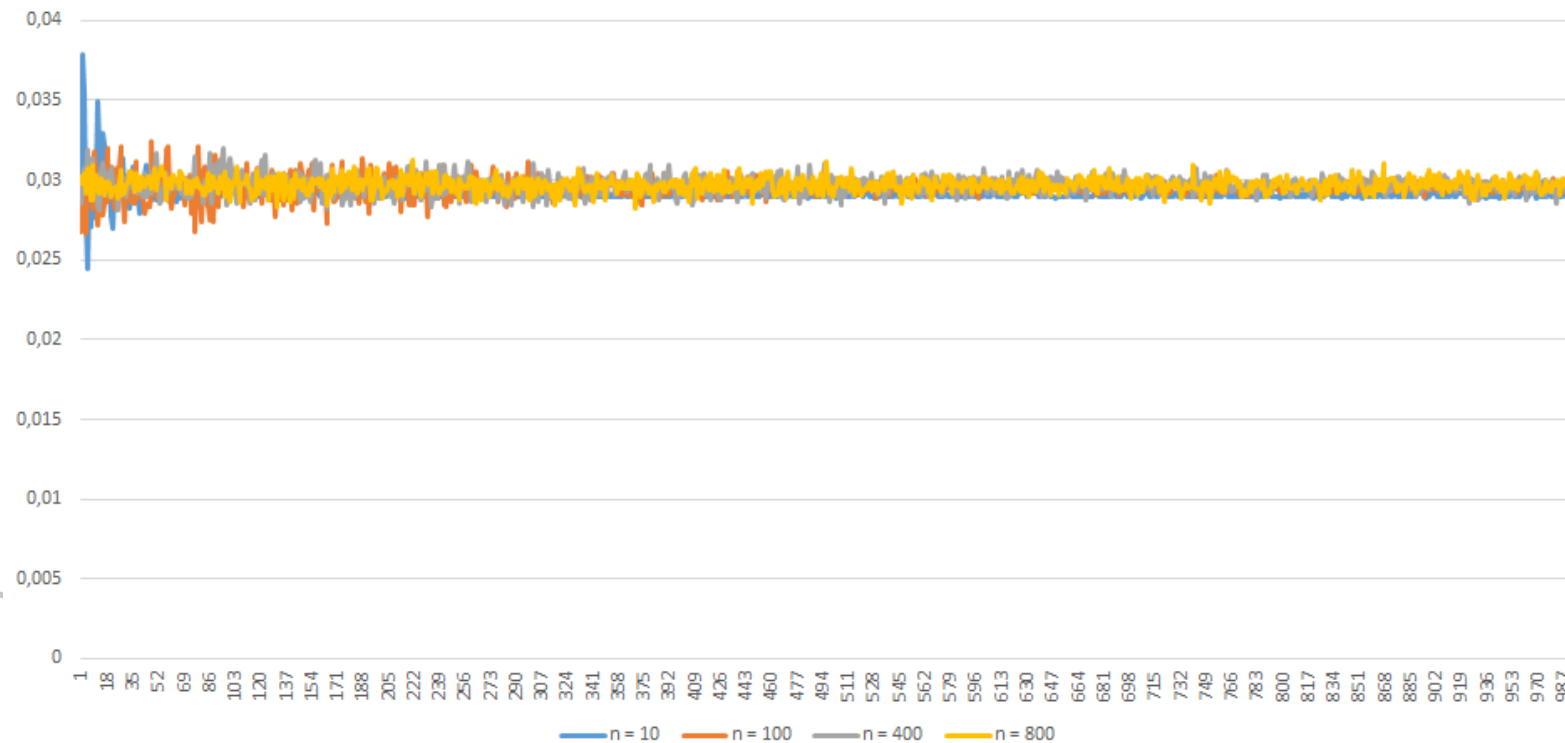
# VARYING #LLOYD ITERATIONS

Results with two random triangles configuration and an obstacle between them



View factor value

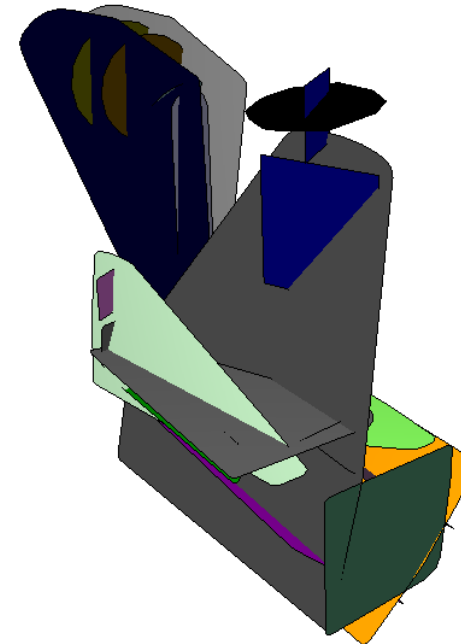
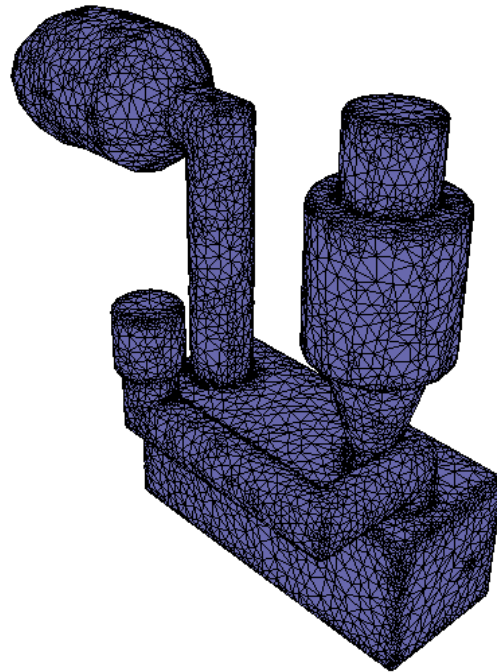
Fixed quad points, incrementing Lloyd iterations (with obstacle)



#Lloyd iterations

	1	2	3	4	5	6	7	8
1	11	12	0	0	0	0	0	0
2	0	22	0	0	0	0	0	0
3	31	32	33	0	0	0	0	0
4	41	42	43	44	0	0	0	0
5	0	0	0	0	55	56	0	0
6	0	0	0	0	0	66	67	0
7	0	0	0	0	0	0	77	78
8	0	0	0	0	0	0	87	88

**Approximation method guided by preservation of the view factors.** We keep the constraint of the thermal nodes in order to compare the matrices of the radiative surfaces per nodes.



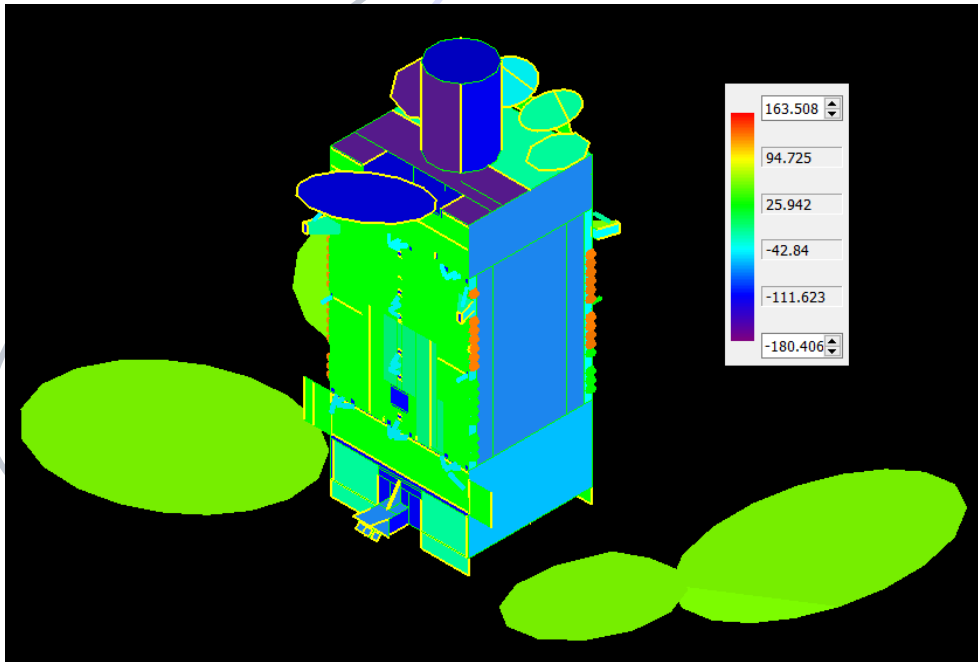


Illustration of the thermal nodes with e-Therm

- ▶ **Simplification** via face clustering in order to best approximate the thermal nodes.
- ▶ **Comparison with the reference calculation thanks to thermal nodes:**
  - ▶ Main idea: compare the radiative surfaces by node matrices from the reference calculation case and the approximation one





- ▶ **Goal:** learn geometric error metric able to govern an automatic approximation algorithm so that the resulting thermal simulation is as accurate as possible to a reference calculation.
- ▶ Constraints = thermal nodes, so we can compare the radiative surfaces of each node before and after approximation.



[[Jacobson](#)] Thingie10K (training dataset)



# THANK YOU



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